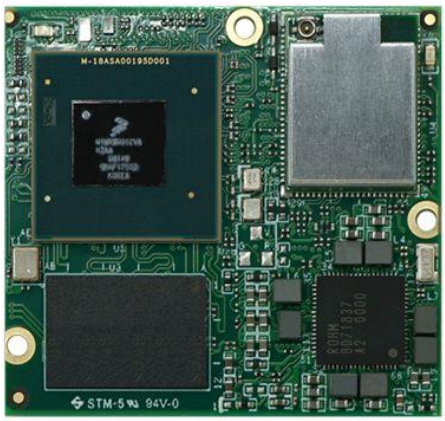

PICO-IMX8M SYSTEM ON MODULE PRODUCT MANUAL

(WITH NXP i.MX8M SoC)

VER. 1.00

January 31, 2020

REVISION HISTORY

Revision	Date	Originator	Notes
0.1	November 6, 2018	TechNexion	Preliminary
0.99	January 14, 2019	TechNexion	Updated PCIe Signals and general release edits
1.00	January 31, 2020	TechNexion	Added connector name labels in figure 5.

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1. Introduction

1.1. General Introduction

The PICO-IMX8M is a high performance highly integrated PICO Compute Module designed around the NXP i.MX8M Dual/QuadLite/Quad core ARM Cortex-A53 + Cortex-M4 applications processor. The PICO-IMX8M provides an ideal building block that easily integrates with a wide range of target markets requiring compact, cost effective with low power consumption.

The modular approach offered by the PICO Compute Module gives your project scalability, fast time to market and upgradability while reducing engineering risk and maintain a competitive total cost of ownership.

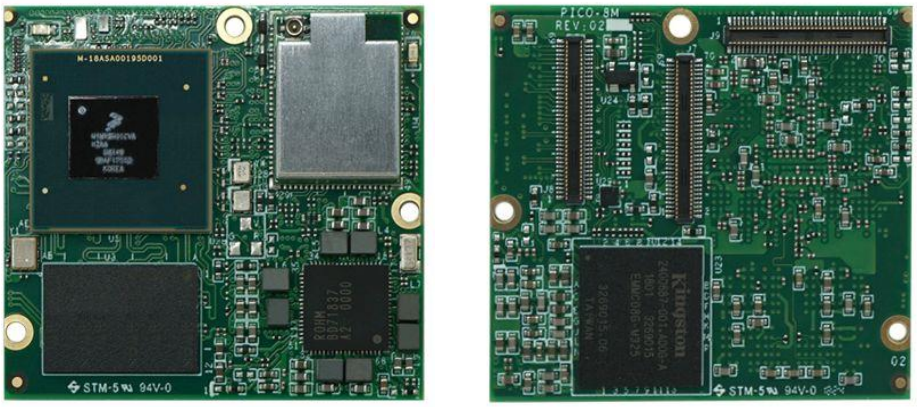
2. PICO-IMX8M Product Overview

The PICO-IMX8M is a high performance, versatile System-on-Module in PICO form factor optimized for the multimedia streaming applications.

2.1. PICO-IMX8M System-on-Module Overview

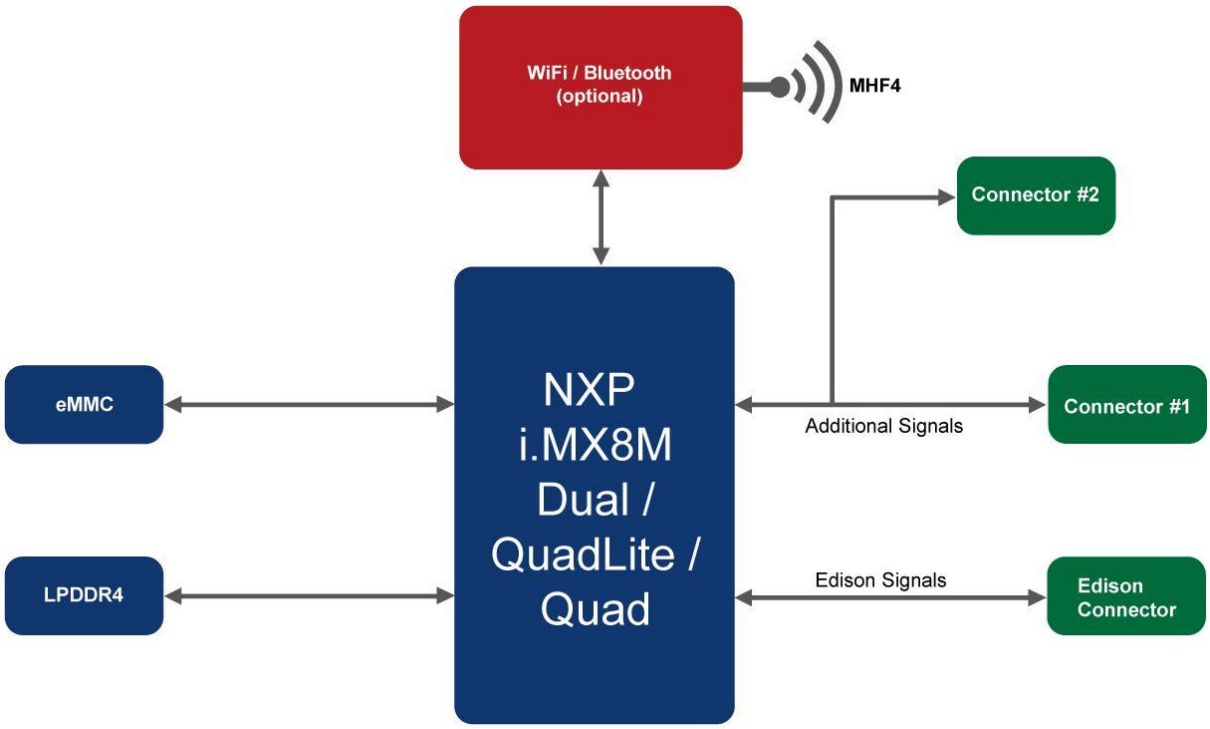
The PICO-IMX8M System-on-Module (PICO-IMX8M) has 3 Hirose high-speed 70 pin board-to-board connectors and integrates the NXP i.MX8M, Memory, eMMC, Power Management IC (PMIC) and Wi-Fi / Bluetooth features.

Figure 1 – PICO-IMX8M System-on-Module



2.2. Block Diagram

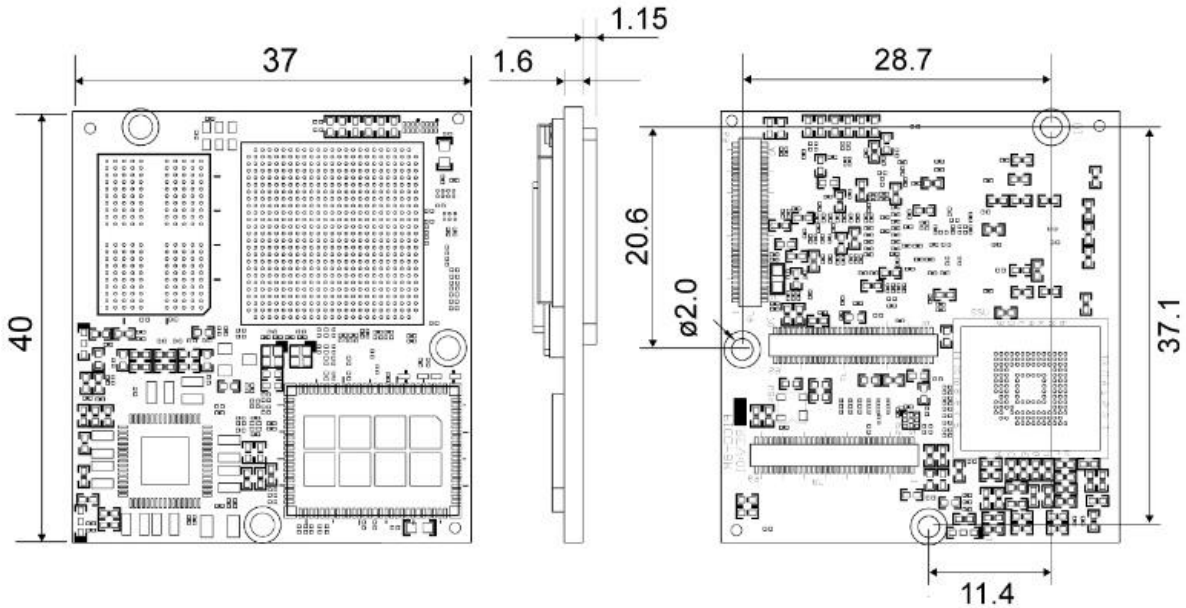
Figure 2 – PICO-IMX8M System-on-Module Block Diagram Overview



2.3. Dimensional Drawing

The PICO-IMX8M System-on-Module is an ultra-compact module in PICO form factor.

Figure 3 – PICO-IMX8M System-on-Module Dimensions



2.4. Component Location

Figure 4 – PICO-IMX8M Top View

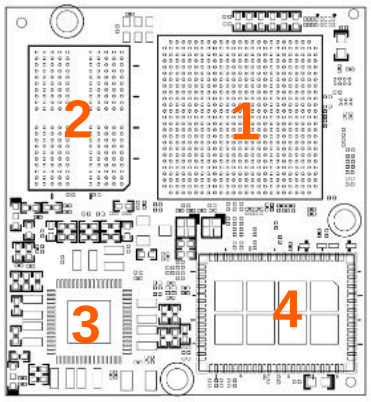
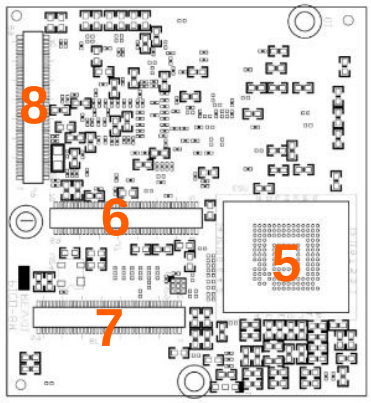


Figure 5 – PICO-IMX8M Bottom View



No.	Description	No.	Description
1	NXP i.MX8M Processor	5	eMMC Storage IC
2	Memory IC	6	Connector E1
3	ROHM BD71837 PMIC	7	Connector X1
4	Wi-Fi/Bluetooth Module (optional)	8	Connector X2

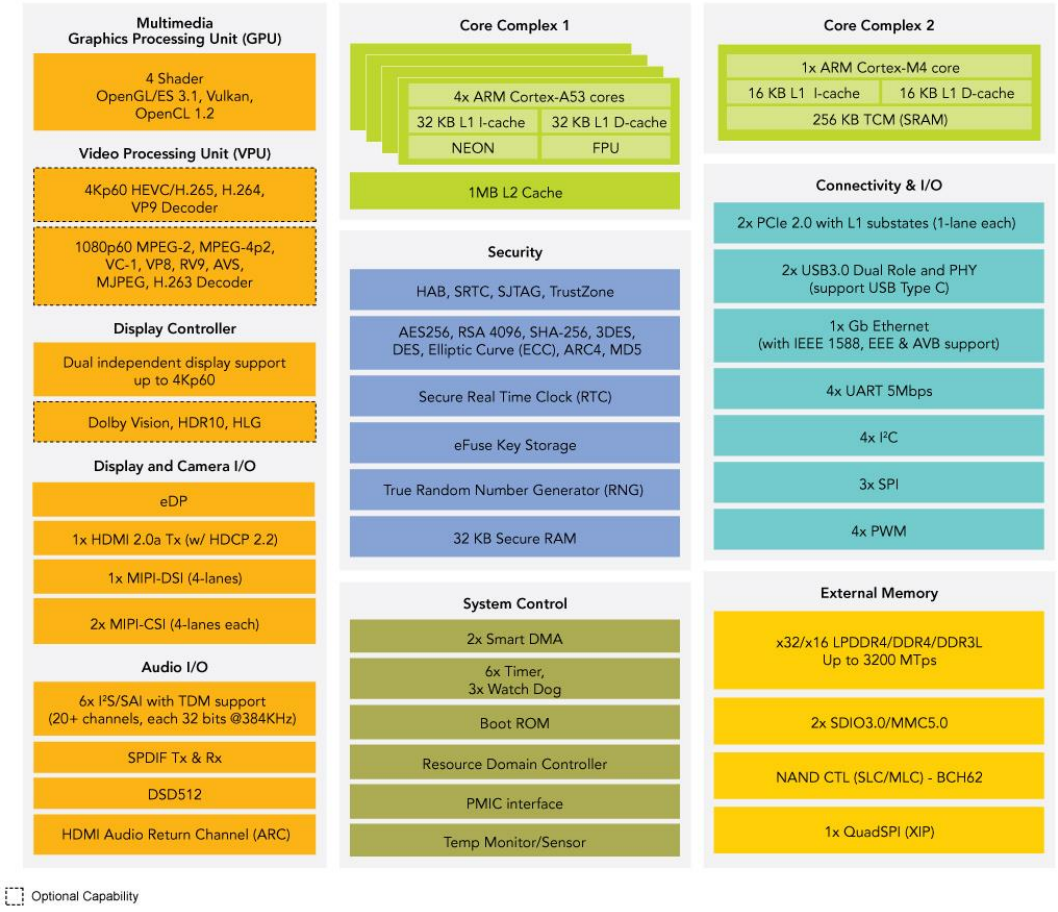
3. Core Components

3.1. NXP i.MX8M ARM Cortex-A53 + Cortex-M4 Processor

The NXP i.MX 8M family of applications processors based on Arm® Cortex®-A53 and Cortex-M4 cores provide industry-leading audio, voice and video processing for applications that scale from consumer home audio, embedded digital signage to industrial building automation control applications.

- HDMI 2.0a, MIPI-DSI Video quality with full 4K UltraHD resolution.
- Highest levels of pro audio fidelity with more than 20 audio channels each @384KHz
- Optimized for fanless operation, low thermal system cost, and long battery life
- Realtime Arm® Cortex-M4 co-processor.

Figure 6 – NXP i.MX8M Processor Blocks



3.2. Power Management IC (ROHM BD71837)

The PICO-IMX8M has an on onboard ROHM BD71837 power management integrated circuit (PMIC) that features a configurable architecture supporting the numerous outputs with various current ratings as well as programmable voltage and sequencing required by the components on the PICO-IMX8M module.

Table 1 – PMIC Signal Description

CPU BALL	CPU PAD NAME	Pinmux (mode)	Signal	V	I/O	Description
E8	I2C1_SDA	I2C1_SDA	SDA	3V3	I/O	I2C bus data line
E7	I2C1_SCL	I2C1_SCL	SCL	3V3	I	I2C bus clock line
W21	ONOFF	PWRON	PWRON_B	3V3	I	PMIC Power ON/OFF Input from processor
W20	POR_B	POR_B	POR_B	3V3	O	PMIC Reset Signal
V20	PMIC_ON_REQ	PMIC_ON_REQ	PMIC_ON_REQ	3V3	I	PMIC Power on request Input from processor
V21	PMIC_STBY_REQ	PMIC_STBY_REQ	PMIC_STBY_REQ	3V3	I	PMIC Power standby request input from processor
P4	GPIO1_IO03	PMIC_nINT	IRQ_B	3V3	O	PMIC Interrupt Signal
W19	RTC_RESET_B	RTC_RESET_B	RTC_RESET_B	3V3	O	PMIC RTC Reset Signal
V22	RTC	CLK_32K	C32K_OUT	3V3	O	32.768 KHz Clock

3.2.1. ROHM BD71837 Reset Signal

To perform a hard-reset of the PICO-IMX8M a software reset signal can be implemented.

Table 2 – PMIC Reset Signal Description

CPU BALL	CPU PAD NAME	Pinmux (mode)	Signal	V	I/O	Description
R4	GPIO1_IO02	nWDOG	WDOG_B	3V3	I	Connected to the WDOG_B signal of PMIC

To perform a hard-reset of the PICO-IMX8M an external circuit (for example a button or external watchdog IC) can be integrated on the carrier board.

Table 3 – PMIC Reset Signal Description

Connector	Signal	V	I/O	Description
E1_36	RESET IN	1V8	I	Connected to Reset Power Signal

3.3. Memory

The PICO-IMX8M integrates Low Power Double Data Rate IV (LPDDR4) Synchronous DRAM is connected with a 32 bit dual channel configuration. (16 bit per channel).

The following memory chip manufacturers have been validated and tested on the PICO-IMX8M Compute Module:

- SKHynix
- Kingston
- Micron
- Samsung
- ISSI

3.4. eMMC Storage

The PICO-IMX8M can be ordered with onboard eMMC storage in different configurations and capacity. The onboard eMMC device is connected on the SD1 pins of the i.MX8M processor in an 8-bit width configuration.

The following eMMC chip manufacturers have been validated and tested on the PICO-IMX8M System-on-Module:

- Kingston eMMC
- Micron eMMC
- Sandisk iNAND

Table 4 – eMMC Signal Description

CPU BALL	CPU PAD NAME	Signal	V	I/O	Description
M25	SD1_DATA0	eMMC_DATA0	1V8	I/O	MMC/SDIO Data bit 0
M24	SD1_DATA1	eMMC_DATA1	1V8	I/O	MMC/SDIO Data bit 1
N25	SD1_DATA2	eMMC_DATA2	1V8	I/O	MMC/SDIO Data bit 2
P25	SD1_DATA3	eMMC_DATA3	1V8	I/O	MMC/SDIO Data bit 3
N24	SD1_DATA4	eMMC_DATA4	1V8	I/O	MMC/SDIO Data bit 4
P24	SD1_DATA5	eMMC_DATA5	1V8	I/O	MMC/SDIO Data bit 5
R25	SD1_DATA6	eMMC_DATA6	1V8	I/O	MMC/SDIO Data bit 6
T25	SD1_DATA7	eMMC_DATA7	1V8	I/O	MMC/SDIO Data bit 7
L24	SD1_CMD	eMMC_CMD	1V8	I/O	MMC/SDIO Command
L25	SD1_CLK	eMMC_CLK	1V8	O	MMC/SDIO Clock
T24	SD1_DS	eMMC_STROBE	1V8	O	This signal is generated by the device and used for output in HS400 Mode

3.5. Wi-Fi/Bluetooth

The PICO-IMX8M has an optional pre-certified high-performance TechNexion PIXI-9377 dual band 2.4/5Ghz Wi-Fi / Bluetooth 5 Qualcomm Atheros QCA9377 chipset based module on board.

The PIXI-9377 Wi-Fi / Bluetooth module is designed to operate with a single antenna for Wi-Fi and Bluetooth by using the MHF4 connector.

Key Features of the PIXI-9377 are:

- IEEE 802.11 ac/a/b/g/n 2.4 / 5Ghz
- Bluetooth 5
- MHF4 antenna connector
- Linux and Android drivers
- Wi-Fi / BT module board certifications with multiple antennas:
    - FCC (USA)
    - IC (Canada
    - ETSI (Europe)
    - Giteki / Telec (Japan)
    - RCM / C-tick (Australia / New Zealand).
- Industrial operation temperature range : -40°C to +85°C

The following pre-certified matching antennas are available with our distributors.

Partnumber	Description
ANTP180A138045D2450MHF4	4.5dBi dipole antenna
ANTP180A207070D2450MHF4	7dBi dipole antenna
ANTP150P232525D2450MHF4	2.5dBi PCB patch antenna

Figure 7 – PICO-IMX8M Wi-Fi Module and Antenna Connector Location

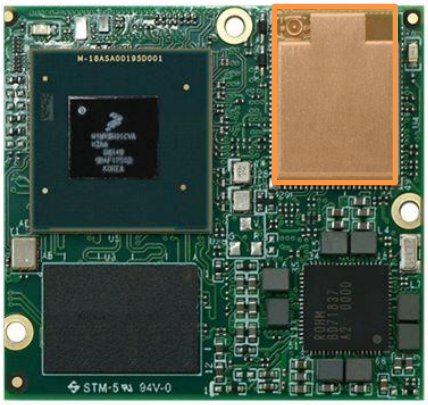


Table 5 – Wi-Fi Signal Description

i.MX8M BALL	PAD NAME	Signal	I/O	Description
N22	SD2_DATA0	SD2_DATA0	I/O	MMC/SDIO Data bit 0
N21	SD2_DATA1	SD2_DATA1	I/O	MMC/SDIO Data bit 1
P22	SD2_DATA2	SD2_DATA2	I/O	MMC/SDIO Data bit 2
P21	SD2_DATA3	SD2_DATA3	I/O	MMC/SDIO Data bit 3
M22	SD2_CMD	SD2_CMD	I/O	MMC/SDIO Command
L22	SD2_CLK	SD2_CLK	O	MMC/SDIO Clock
N4	SAI5_RXFS	GPIO3_IO19 WL_HOST_WAKE	O	Host wake up. Signal from the module to the host indicating that the module requires Attention. • Asserted: Host device must wake-up or remain awake. • Deserted: Host device may sleep when sleep criteria are met. The polarity of this signal is software configurable and can be asserted high or low.
K5	SAI5_RXD3	GPIO3_IO24 WL_REG_ON	O	Wi-Fi device wake-up: Signal from the host to the module indicating that the host requires attention. • Asserted: Wi-Fi device must wake-up or remain awake. • Deserted: Wi-Fi device may sleep when sleep criteria are met. The polarity of this signal is software configurable and can be asserted high or low.

Table 6 – Bluetooth Signal Description

i.MX8M BALL	PAD NAME	Signal	I/O	Description
D6	UART2_TXD	UART2_TXD	O	Bluetooth UART Serial Input. Serial data input for the HCI UART Interface
B6	UART2_RXD	UART2_RXD	I	Bluetooth UART Serial Output. Serial data output for the HCI UART Interface.
C6	UART4_RXD	UART2_CTS	I/O	Bluetooth UART Clear to Send. Active-low clear-to-send signal for the HCI UART interface.
D7	UART4_TXD	UART2_RTS	I/O	Bluetooth UART Request to Send. Active-low request-to-send signal for the HCI UART interface.
K2	SAI1_RXD0	SAI1_RXD0	I	Integrated Interchip Sound (I^2S) channel receive data line
F2	SAI1_TXD0	SAI1_TXD0	O	Integrated Interchip Sound (I^2S) channel transmit data line
E1	SAI1_TXC	SAI1_TXC	O	Integrated Interchip Sound (I^2S) channel word clock signal
H1	SAI1_TXFS	SAI1_TXFS	O	Integrated Interchip Sound (I^2S) channel frame synchronization signal
L5	SAI5_RXC	GPIO3_IO20 BT_HOST_WAKE	I	Host UART wake up. Signal from the module to the host indicating that the module requires Attention. • Asserted: Host device must wake-up or remain awake. • Deserted: Host device may sleep when sleep criteria are met. The polarity of this signal is software configurable and can be asserted high or low.
M5	SAI5_RXD0	GPIO3_IO21 BT_DEV_WAKE	O	Bluetooth device wake-up: Signal from the host to the module indicating that the host requires attention. • Asserted: Bluetooth device must wake-up or remain awake. • Deserted: Bluetooth device may sleep when sleep criteria are met. The polarity of this signal is software configurable and can be asserted high or low.

4. PICO Compute Module Pin Assignment

The PICO-IMX8M has three 70-pin Hirose board-to-board connectors.

Figure 8 – PICO-IMX8M Board-to-Board Connectors

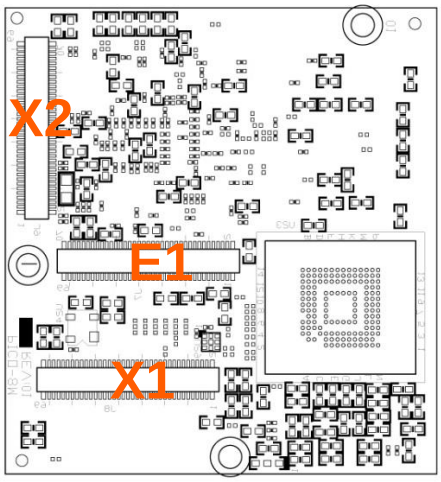


Table 7 – PICO Compute Module Pin Assignment

PIN	CPU BALL	CPU PAD NAME	Signal	V	I/O	Description
E1_1		GND	GND		P	Ground
E1_2			VSYS		P	System input power (4.2 to 5.25V)
E1_3	C14	USB1_ID	USB1_ID	3V3	I	USB OTG ID Pin
E1_4			VSYS		P	System input power (4.2 to 5.25V)
E1_5		GND	GND		P	Ground
E1_6			VSYS		P	System input power (4.2 to 5.25V)
E1_7			NC			Not Connected
E1_8		VDD_3V3	VDD_3V3	3V3	P	System 3.3V Output
E1_9		GND	GND		P	Ground
E1_10		VDD_3V3	VDD_3V3	3V3	P	System 3.3V Output
E1_11		GND	GND		P	Ground
E1_12		VDD_1V8	VDD_1V8	1V8	P	System 1.8V Output (same as E1 connector I/O voltage levels)
E1_13		GND	GND		P	Ground
E1_14			VSYS		P	System input power (4.2 to 5.25V)
E1_15		GND	GND		P	Ground
E1_16	A14	USB1_DP	USB1_DP	3V3	I/O	Universal Serial Bus differential pair positive signal
E1_17	W21	ONOFF	ONOFF	3V3	I	Power ON button input signal
E1_18	B14	USB1_DN	USB1_DN	3V3	I/O	Universal Serial Bus differential pair negative signal

E1_19	G4	SAI3_RXFS	GPIO4_IO28	1V8	I	Over current detect input pin to monitor USB power over current
E1_20	D14	USB1_VBUS	USB_VBUS	5V	I/O	Universal Serial Bus power
E1_21	M20	NAND_DQS	GPIO3_IO14	1V8	O	Universal Serial Bus power enable
E1_22	C7	UART1_RXD	UART1_RXD	1V8	I	Universal Asynchronous Receive Transmit receive data signal
E1_23			NC			Not Connected
E1_24	H19	NAND_CE0_B	GPIO3_IO01	1V8	I/O	General Purpose Input Output
E1_25	F21	AND_CE2_B	GPIO3_IO03	1V8	I/O	General Purpose Input Output
E1_26	H20	NAND_CE3_B	GPIO3_IO04	1V8	I/O	General Purpose Input Output
E1_27	A7	UART1_TXD	UART1_TXD	1V8	O	Universal Asynchronous Receive Transmit transmit data signal
E1_28	G19	NAND_ALE	GPIO3_IO00	1V8	I/O	General Purpose Input Output
E1_29	P5	GPIO1_IO04	GPIO1_IO04	3V3	O	SD Card voltage select
E1_30	H21	NAND_CLE	GPIO3_IO05	1V8	I/O	General Purpose Input Output
E1_31			NC			Not Connected
E1_32	K19	NAND_RE_B	GPIO3_IO15	1V8	I/O	General Purpose Input Output
E1_33	G6	SPDIF_RX	PWM2_OUT	1V8	O	General Purpose Input Output with PWM control
E1_34	K22	NAND_WE_B	GPIO3_IO17	1V8	I/O	General Purpose Input Output
E1_35	E6	SPDIF_EXT_CLK	PWM1_OUT	1V8	O	General Purpose Input Output with PWM control
E1_36			RESET IN	1V8	I	Reset power signal
E1_37	F6	SPDIF_TX	PWM3_OUT	1V8	I/O	General Purpose Input Output with PWM control
E1_38	V1	HDMI_AUX_P	HDMI_AUXP	1V8	I/O	Carries the HEAC positive signal - HDMI Ethernet Audio Channel
E1_39	D3	SAI3_MCLK	PWM4_OUT	1V8	O	General Purpose Input Output with PWM control
E1_40	V2	HDMI_AUX_N	HDMI_AUXN	1V8	I/O	Carries the HEAC negative signal - HDMI Ethernet Audio Channel
E1_41	G7	I2C2_SCL	I2C2_SCL	1V8	O	I2C bus clock line
E1_42	K21	NAND_WP_B	GPIO3_IO18	1V8	I/O	General Purpose Input Output
E1_43	F7	I2C2_SDA	I2C2_SDA	1V8	I/O	I2C bus data line
E1_44	K20	NAND_READY_B	GPIO3_IO16	1V8	I/O	General Purpose Input Output
E1_45	G8	I2C3_SCL	I2C3_SCL	1V8	O	I2C bus clock line
E1_46	E5	ECSPI2_MOSI	UART4_TXD	1V8	O	Universal Asynchronous Receive Transmit transmit data signal
E1_47	E9	I2C3_SDA	I2C3_SDA	1V8	I/O	I2C bus data line
E1_48	G20	NAND_DATA00	GPIO3_IO06	1V8	I/O	General Purpose Input Output
E1_49			NVCC_SD	1V8 / 3V3	P	SD Card power

E1_50	F3	SAI3_RXD	SAI3_RXD	1V8	I	Integrated Interchip Sound (I2S) channel receive data line
E1_51	G21	NAND_CE1_B	ECSPI1_SS1	1V8	O	Serial Peripheral Interface Chip Select 1 signal
E1_52	C4	SAI3_TXC	SAI3_TXC	1V8	O	Integrated Interchip Sound (I2S) channel word clock signal
E1_53	D4	ECSPI1_SS0	ECSPI1_SS0	1V8	O	Serial Peripheral Interface Chip Select 0 Signal
E1_54	G3	SAI3_TXFS	SAI3_TXFS	1V8	O	Integrated Interchip Sound (I2S) channel frame synchronization signal
E1_55	D5	ECSPI1_SCLK	ECSPI1_SCLK	1V8	O	Serial Peripheral Interface clock signal
E1_56	C3	SAI3_TXD	SAI3_TXD	1V8	O	Integrated Interchip Sound (I2S) channel transmit data line
E1_57	A4	ECSPI1_MOSI	ECSPI1_MOSI	1V8	O	Serial Peripheral Interface master output slave input signal.
E1_58	L22	SD2_CLK	SD2_CLK	1V8/ 3V3	O	MMC/SDIO Clock
E1_59	B4	ECSPI1_MISO	ECSPI1_MISO	1V8	I/O	Serial Peripheral Interface master input slave output signal
E1_60	L21	SD2_CD_B	SD2_CD	1V8/ 3V3	I	SD Card detect input (Active low)
E1_61	C5	ECSPI2_SCLK	UART4_RXD	1V8	I	Universal Asynchronous Receive Transmit receive data signal
E1_62	M22	SD2_CMD	SD2_CMD	1V8/ 3V3	I/O	MMC/SDIO Command
E1_63	A5	ECSPI2_SS0	UART4_RTS	1V8	O	Universal Asynchronous Receive Transmit request to send signal
E1_64	P22	SD2_DATA2	SD2_DATA2	1V8/ 3V3	I/O	MMC/SDIO Data bit 2
E1_65	B5	ECSPI2_MISO	UART4_CTS	1V8	O	Universal Asynchronous Receive Transmit clear to send signal
E1_66	N22	SD2_DATA0	SD2_DATA0	1V8/ 3V3	IO	MMC/SDIO Data bit 0
E1_67			NC			Not Connected
E1_68	P21	SD2_DATA3	SD2_DATA3	1V8/ 3V3	I/O	MMC/SDIO Data bit 3
E1_69			NC			Not Connected
E1_70	N21	SD2_DATA1	SD2_DATA1	1V8/ 3V3	I/O	MMC/SDIO Data bit 1

PIN	CPU BALL	CPU PAD NAME	Signal	V	I/O	Description
X1_1			GND		P	Ground
X1_2			GND		P	Ground
X1_3	C19	CSI2_D3_N	CSI_P2_DN3	1V8	I	MIPI Camera 2 Serial Interface data pair 3 negative signal
X1_4	B7	UART3_TXD	GPIO5_IO27	3V3	O	General Purpose Input Output for MIPI Camera 2 power down
X1_5	D19	CSI2_D3_P	CSI_P2_DP3	1V8	I	MIPI Camera 2 Serial Interface data pair 3 positive signal
X1_6	N6	GPIO1_IO07	GPIO1_IO07	3V3	I/O	General Purpose Input Output for MIPI Display Touchscreen Interupt
X1_7			GND		P	Ground
X1_8			NC			Not Connected
X1_9	A19	CSI2_CLK_N	CSI_P2_CKN	1V8	I	MIPI Camera 2 Serial Interface clock pair negative signal
X1_10			NC			Not Connected
X1_11	B19	CSI2_CLK_P	CSI_P2_CKP	1V8	I	MIPI Camera 2 Serial Interface clock pair positive signal
X1_12			NC			Not Connected
X1_13			GND		P	Ground
X1_14			NC			Not Connected
X1_15	A21	CSI2_D2_N	CSI_P2_DN2	1V8	I	MIPI Camera 2 Serial Interface data pair 2 negative signal
X1_16			NC			Not Connected
X1_17	B21	CSI2_D2_P	CSI_P2_DP2	1V8	I	MIPI Camera 2 Serial Interface data pair 2 positive signal
X1_18			NC			Not Connected
X1_19			GND		P	Ground
X1_20			NC			Not Connected
X1_21	A20	CSI2_D1_N	CSI_P2_DN1	1V8	I	MIPI Camera 2 Serial Interface data pair 1 negative signal
X1_22			NC			Not Connected
X1_23	B20	CSI2_D1_P	CSI_P2_DP1	1V8	I	MIPI Camera 2 Serial Interface data pair 1 positive signal
X1_24			NC			Not Connected
X1_25			GND		P	Ground
X1_26			NC			Not Connected
X1_27	C20	CSI2_D0_N	CSI_P2_DN0	1V8	I	MIPI Camera 2 Serial Interface data pair 0 negative signal
X1_28			NC			Not Connected
X1_29	D20	CSI2_D0_P	CSI_P2_DP0	1V8	I	MIPI Camera 2 Serial Interface data pair 0 positive signal
X1_30			NC			Not Connected
X1_31			GND		P	Ground
X1_32			NC			Not Connected

X1_33	N20	ENET_MDC	ENET_MDC	2V5	O	Management data clock reference
X1_34			NC			Not Connected
X1_35	N19	NET_MDIO	ENET_MDIO	2V5	I/O	Management data
X1_36			NC			Not Connected
X1_37	M6	GPIO1_IO09	GPIO1_IO09	3V3	O	Ethernet reset
X1_38			NC			Not Connected
X1_39	L6	GPIO1_IO11	GPIO1_IO11	3V3	I	Ethernet interrupt output
X1_40			NC			Not Connected
X1_41	T6	GPIO1_IO00	RGMII_REF_CLK	3V3	O	Synchronous Ethernet recovered clock
X1_42			NC			Not Connected
X1_43	P19	ENET_TX_CTL	ENET_TX_CTL	2V5	O	RGMII transmit enable
X1_44			NC			Not Connected
X1_45	T21	ENET_RX_CTL	ENET_RX_CTL	2V5	I	RGMII receive data valid
X1_46			NC			Not Connected
X1_47			GND		P	Ground
X1_48			NC			Not Connected
X1_49	T19	ENET_TXC	ENET_TXC	2V5	O	RGMII transmit clock
X1_50			NC			Not Connected
X1_51	R20	ENET_TD0	ENET_TD0	2V5	O	RGMII transmit data 0
X1_52			NC			Not Connected
X1_53	R21	ENET_TD1	ENET_TD1	2V5	O	RGMII transmit data 1
X1_54			NC			Not Connected
X1_55	R19	ENET_TD2	ENET_TD2	2V5	O	RGMII transmit data 2
X1_56			NC			Not Connected
X1_57	P20	ENET_TD0	ENET_TD3	2V5	O	RGMII transmit data 3
X1_58			NC			Not Connected
X1_59			GND		P	Ground
X1_60			NC			Not Connected
X1_61	T20	ENET_RXC	ENET_RXC	2V5	I	RGMII receive clock
X1_62			NC			Not Connected
X1_63	U19	ENET_RD0	ENET_RD0	2V5	I	RGMII receive data 0
X1_64			NC			Not Connected
X1_65	U21	ENET_RD1	ENET_RD1	2V5	I	RGMII receive data 1
X1_66	T7	GPIO1_IO01	PWM1_OUT	3V3	I/O	General Purpose Input Output with PWM control for MIPI DSI Brightness Control
X1_67	U20	ENET_RD2	ENET_RD2	2V5	I	RGMII receive data 2
X1_68	N7	GPIO1_IO08	DSI_EN	3V3	I/O	General Purpose Input Output to enable MIP DSI Display
X1_69	V19	ENET_RD3	ENET_RD3	2V5	I	RGMII receive data 3
X1_70			GND		P	Ground

PIN	CPU BALL	CPU PAD NAME	Signal	V	I/O	Description
X2_1			GND		P	Ground
X2_2			GND		P	Ground
X2_3	J1	SAI1_RXD4	BT_CFG4	3V3	I	Boot Select pin
	B2	SAI1_TXD2	BT_CFG10	3V3	I	Boot Select pin
	D2	SAI1_TXD4	BT_CFG12	3V3	I	Boot Select pin
X2_4	A18	DSI_D2_N	DSI_DN2	1V8	O	MIPI Display Serial Interface data pair 2 negative signal
X2_5	W6	BOOT_MODE0	BOOT_MODE0	3V3	I	Boot Select pin
X2_6	B18	DSI_D2_P	DSI_DP2	1V8	O	MIPI Display Serial Interface data pair 2 positive signal
X2_7	C2	SAI1_TXD5	BT_CFG13	3V3	I	Boot Select pin
	F1	SAI1_RXD5	BT_CFG5	3V3	I	Boot Select pin
X2_8			GND		P	Ground
X2_9	V6	BOOT_MODE1	BOOT_MODE1	3V3	I	Boot Mode1 select
X2_10	A15	DSI_D3_N	DSI_DN3	1V8	O	MIPI Display Serial Interface data pair 3 negative signal
X2_11			GND		P	Ground
X2_12	B15	DSI_D3_P	DSI_DP3	1V8	O	MIPI Display Serial Interface data pair 3 positive signal
X2_13	R3	HDMI_DDC_SCL	HDMI_DDC_SCL	1V8	O	HDMI DDC bus clock line
X2_14			GND		P	Ground
X2_15	P3	HDMI_DDC_SDA	HDMI_DDC_SDA	1V8	I/O	HDMI DDC bus data line
X2_16	T1	HDMI_TX_P_LN_0	HDMI_TXP0	1V8	O	HDMI differential pair 0 positive signal
X2_17			GND		P	Ground
X2_18	T2	HDMI_TX_M_LN_0	HDMI_TXN0	1V8	O	HDMI differential pair 0 negative signal
X2_19	G5	SAI2_TXD0	SAI2_TXD	3V3	O	Integrated Interchip Sound (I2S) channel transmit data line
X2_20			GND		P	Ground
X2_21	H6	SAI2_RXD0	SAI2_RXD	3V3	I	Integrated Interchip Sound (I^2S) channel receive data line
X2_22	U2	HDMI_TX_P_LN_1	HDMI_TXP1	1V8	O	HDMI differential pair 1 positive signal
X2_23			GND		P	Ground
X2_24	U1	HDMI_TX_M_LN_1	HDMI_TXN1	1V8	O	HDMI differential pair 1 negative signal
X2_25	H4	SAI2_TXFS	SAI2_TXFS	3V3	O	Integrated Interchip Sound (I^2S) channel frame synchronization signal
X2_26			GND		P	Ground
X2_27	J5	SAI2_TXC	SAI2_TXC	3V3	O	Integrated Interchip Sound (I^2S) channel word clock signal
X2_28	N2	HDMI_TX_P_LN_2	HDMI_TXP2	1V8	O	HDMI differential pair 2 positive signal
X2_29			GND		P	Ground

X2_30	N1	HDMI_TX_M_LN_2	HDMI_TXN2	1V8	O	HDMI differential pair 2 negative signal
X2_31	A22	CSI1_CLK_N	CSI_P1_CKN	1V8	O	MIPI Camera 1 Serial Interface clock pair negative signal
X2_32			GND		P	Ground
X2_33	B22	CSI1_CLK_P	CSI_P1_CKP	1V8	O	MIPI Camera 1 Serial Interface clock pair positive signal
X2_34	M1	HDMI_TX_P_LN_3	HDMI_CLKP	1V8	O	HDMI differential pair clock positive signal
X2_35	A23	CSI1_D0_N	CSI_P1_DN0	1V8	I	MIPI Camera 1 Serial Interface data pair 0 negative signal
X2_36	M2	HDMI_TX_M_LN_3	HDMI_CLKN	1V8	O	HDMI differential pair clock negative signal
X2_37	B23	CSI1_D0_P	CSI_P1_DP0	1V8	I	MIPI Camera 1 Serial Interface data pair 0 positive signal
X2_38			GND		P	Ground
X2_39	D22	CSI1_D1_P	CSI_P1_DP1	1V8	I	MIPI Camera 1 Serial Interface data pair 1 positive signal
X2_40	W3	HDMI_CEC	HDMI_CEC	1V8	I/O	HDMI Consumer Electronics Control
X2_41	C22	CSI1_D1_N	CSI_P1_DN1	1V8	I	MIPI Camera 1 Serial Interface data pair 1 negative signal
X2_42	W2	HDMI_HPD	HDMI_HPD	1V8	I	HDMI/DP Hot plug detection signal that serves as an interrupt request
X2_43	C23	CSI1_D2_P	CSI_P1_DP2	1V8	I	MIPI Camera 1 Serial Interface data pair 2 positive signal
X2_44			GND		P	Ground
X2_45	B24	CSI1_D2_N	CSI_P1_DN2	1V8	I	MIPI Camera 1 Serial Interface data pair 2 negative signal
X2_46	B10	USB2_DN	USB2_DN	3V3	I/O	Universal Serial Bus differential pair negative signal
X2_47	C21	CSI1_D3_N	CSI_P1_DN3	1V8	I	MIPI Camera 1 Serial Interface data pair 3 negative signal
X2_48	A10	USB2_DP	USB2_DP	3V3	I/O	Universal Serial Bus differential pair positive signal
X2_49	D21	CSI1_D3_P	CSI_P1_DP3	1V8	I	MIPI Camera 1 Serial Interface data pair 3 positive signal
X2_50	D9	USB2_VBUS	USB2_VBUS	5V	I	Universal Serial Bus power
X2_51			GND		P	Ground
X2_52	P7	GPIO1_IO05	GPIO1_IO05	3V3	I	General Purpose Input Output for Active low input, to inform USB overcurrent condition

						(low = overcurrent detected)
X2_53	B17	DSI_D0_P	DSI_DP0	1V8	O	MIPI Display Serial Interface data pair 0 positive signal
X2_54			GND		P	Ground
X2_55	A17	DSI_D0_N	DSI_DN0	1V8	O	MIPI Display Serial Interface data pair 0 negative signal
X2_56	T22	CLK2_P	PCIE2_CLKP	3V3	O	PCI Express clock differential pair positive signal
X2_57	B16	DSI_D1_P	DSI_DP1	1V8	O	MIPI Display Serial Interface data pair 1 positive signal
X2_58	U22	CLK2_N	PCIE2_CLKN	3V3	O	PCI Express clock differential pair negative signal
X2_59	A16	DSI_D1_N	DSI_DN1	1V8	O	MIPI Display Serial Interface data pair 1 negative signal
X2_60			GND		P	Ground
X2_61	C16	DSI_CLK_N	DSI_CKN	1V8	O	MIPI Display Serial Interface clock pair negative signal
X2_62	E25	PCIE2_TXN_P	PCIE2_TXP	3V3	O	PCI Express Receive input differential pair positive signal
X2_63	D16	DSI_CLK_P	DSI_CKP	1V8	O	MIPI Display Serial Interface clock pair positive signal
X2_64	E24	PCIE2_TXN_N	PCIE2_TXN	3V3	O	PCI Express Receive input differential pair negative signal
X2_65	L7	GPIO1_IO12	GPIO1_IO12	3V3	O	General Purpose Input Output for MIPI Camera reset
X2_66			GND		P	Ground
X2_67	A6	UART3_RXD	GPIO5_IO26	3V3	O	General Purpose Input Output for MIPI Camera 1 power down
X2_68	D25	PCIE_RXN_P	PCIE2_RXP	3V3	I	PCI Express Receive input differential pair positive signal
X2_69	J6	GPIO1_IO15	CLKO2	3V3	O	MIPI Camera input clock
X2_70	D24	PCIE_RXN_N	PCIE2_RXN	3V3	I	PCI Express Receive input differential pair negative signal

5. PICO Compute Module Connector Interfaces

5.1. Ethernet

The PICO-IMX8M provides a 10/100/1000-Mbit/s MAC ethernet interface which, implements layer 3 network acceleration functions. These functions are designed to accelerate the processing of various common networking protocols, such as IP, TCP, UDP, and ICMP, providing wire speed services to client applications.

The Ethernet interface provides following features.

- triple speed 10/100/1000 Mbit/s Ethernet MAC compliant with the IEEE802.3-2002 standard.
- The MAC layer provides compatibility with half- or full-duplex 10/100 Mbit/s Ethernet LANs and full-duplex gigabit Ethernet LANs.

For additional details, please refer to the “Ethernet MAC (ENET)” chapter of the “i.MX8M Reference Manual”.

Table 8 - Ethernet Signal Description

PIN	CPU BALL	CPU PAD NAME	Signal	V	I/O	Description
X1_33	N20	ENET_MDC	ENET_MDC	2V5	O	Management data clock reference
X1_35	N19	NET_MDIO	ENET_MDIO	2V5	I/O	Management data
X1_37	M6	GPIO1_IO09	GPIO1_IO09	3V3	O	Ethernet reset
X1_39	L6	GPIO1_IO11	GPIO1_IO11	3V3	I	Ethernet interrupt output
X1_41	T6	GPIO1_IO00	RGMII_REF_CLK	3V3	O	Synchronous Ethernet recovered clock
X1_43	P19	ENET_TX_CTL	ENET_TX_CTL	2V5	O	RGMII transmit enable
X1_45	T21	ENET_RX_CTL	ENET_RX_CTL	2V5	I	RGMII receive data valid
X1_49	T19	ENET_TXC	ENET_TXC	2V5	O	RGMII transmit clock
X1_51	R20	ENET_TD0	ENET_TD0	2V5	O	RGMII transmit data 0
X1_53	R21	ENET_TD1	ENET_TD1	2V5	O	RGMII transmit data 1
X1_55	R19	ENET_TD2	ENET_TD2	2V5	O	RGMII transmit data 2
X1_57	P20	ENET_TD0	ENET_TD3	2V5	O	RGMII transmit data 3
X1_61	T20	ENET_RXC	ENET_RXC	2V5	I	RGMII receive clock
X1_63	U19	ENET_RD0	ENET_RD0	2V5	I	RGMII receive data 0
X1_65	U21	ENET_RD1	ENET_RD1	2V5	I	RGMII receive data 1
X1_67	U20	ENET_RD2	ENET_RD2	2V5	I	RGMII receive data 2
X1_69	V19	ENET_RD3	ENET_RD3	2V5	I	RGMII receive data 3

5.1. HDMI

The PICO-IMX8M provides an HDMI 2.0 interface directly from the NXP i.MX8M SoC.

The HDMI interface provides following features.

- HDMI 1.4 and HDMI 2.0 Specifications upto 4096*2160p60
- Display Port 1.3
- eDP 1.4

NOTE : Display Port and eDP interfaces are not validated on TechNexion carrier board and awaits NXP formal documentation and software release.

For additional details, please refer to the “HD Display Transmitter Controller (HDMI TX)” chapter of the “i.MX8M Reference Manual”.

Table 9 - HDMI Signal Description

PIN	CPU BALL	CPU PAD NAME	Signal	V	I/O	Description
E1_38	V1	HDMI_AUX_P	HDMI_AUXP	1V8	I/O	Carries the HEAC positive signal - HDMI Ethernet Audio Channel
E1_40	V2	HDMI_AUX_N	HDMI_AUXN	1V8	I/O	Carries the HEAC negative signal - HDMI Ethernet Audio Channel
X2_13	R3	HDMI_DDC_SCL	HDMI_DDC_SCL	1V8	O	HDMI DDC bus clock line
X2_15	P3	HDMI_DDC_SDA	HDMI_DDC_SDA	1V8	I/O	HDMI DDC bus data line
X2_16	T1	HDMI_TX_P_LN_0	HDMI_TXP0	1V8	O	HDMI differential pair 0 positive signal
X2_18	T2	HDMI_TX_M_LN_0	HDMI_TXN0	1V8	O	HDMI differential pair 0 negative signal
X2_22	U2	HDMI_TX_P_LN_1	HDMI_TXP1	1V8	O	HDMI differential pair 1 positive signal
X2_24	U1	HDMI_TX_M_LN_1	HDMI_TXN1	1V8	O	HDMI differential pair 1 negative signal
X2_28	N2	HDMI_TX_P_LN_2	HDMI_TXP2	1V8	O	HDMI differential pair 2 positive signal
X2_30	N1	HDMI_TX_M_LN_2	HDMI_TXN2	1V8	O	HDMI differential pair 2 negative signal
X2_34	M1	HDMI_TX_P_LN_3	HDMI_CLKP	1V8	O	HDMI differential pair clock positive signal
X2_36	M2	HDMI_TX_M_LN_3	HDMI_CLKN	1V8	O	HDMI differential pair clock negative signal
X2_40	W3	HDMI_CEC	HDMI_CEC	1V8	I/O	HDMI Consumer Electronics Control
X2_42	W2	HDMI_HPD	HDMI_HPD	1V8	I	HDMI/DP Hot plug detection signal that serves as an interrupt request

5.2. MIPI Display

The Mobile Industry Processor Interface (MIPI) Display Serial Interface (DSI) controller is a flexible, high-performance, and easy-to-use digital core that implements all protocol functions defined in the MIPI DSI Specification. The MIPI DSI controller provides an interface that allows communication with MIPI DSI-compliant peripherals. The MIPI DSI D-PHY is a high frequency, low power, low-cost, source-synchronous, physical layer supporting the MIPI Alliance standard for D-PHY.

Key features of the MIPI DSI Controller Core include:

- Implements all three DSI Layers (Pixel to Byte packing, Low Level Protocol, Lane Management)
- Support for Command and Video Modes
- Host Version
- Scalable data lane support, 1 to 4 Data Lanes
- Optional bidirectional support on lane 0
- Supports High Speed and Low Power operation
- Support for all DSI data types and formats
- Virtual Channel support
- Supports ULPS mode
- Full Low-Level Protocol Error and Contention detection and reporting
- Supports continuous and non-continuous Clock Lane operation
- Supports multiple packets per transmission
- Support for all three Video Mode packet sequences
  - Non-Burst Mode with Sync Pulses
  - Non-Burst Mode with Sync Events
  - Burst mode
- Support for bus turnaround signaling
- Flexible packet based user interface
- APB interface option (status and control)
- Display Pixel Interface Core (DPI-2) option
- Display Bus Interface Core (DBI-2) option
- Supports PHY Protocol Interface (PPI) compatible MIPI D-PHYs
- MIPI Alliance Specification for Display Serial Interface Version 1.1 compliant

Table 10 - MIPI Display Signal Description

PIN	CPU BALL	CPU PAD NAME	Signal	V	I/O	Description
X2_4	A18	DSI_D2_N	DSI_DN2	1V8	O	MIPI Display Serial Interface data pair 2 negative signal
X2_6	B18	DSI_D2_P	DSI_DP2	1V8	O	MIPI Display Serial Interface data pair 2 positive signal
X2_10	A15	DSI_D3_N	DSI_DN3	1V8	O	MIPI Display Serial Interface data pair 3 negative signal
X2_12	B15	DSI_D3_P	DSI_DP3	1V8	O	MIPI Display Serial Interface data pair 3 positive signal
X2_53	B17	DSI_D0_P	DSI_DP0	1V8	O	MIPI Display Serial Interface data pair 0 positive signal
X2_55	A17	DSI_D0_N	DSI_DN0	1V8	O	MIPI Display Serial Interface data pair 0 negative signal

X2_57	B16	DSI_D1_P	DSI_DP1	1V8	O	MIPI Display Serial Interface data pair 1 positive signal
X2_59	A16	DSI_D1_N	DSI_DN1	1V8	O	MIPI Display Serial Interface data pair 1 negative signal
X2_61	C16	DSI_CLK_N	DSI_CKN	1V8	O	MIPI Display Serial Interface clock pair negative signal
X2_63	D16	DSI_CLK_P	DSI_CKP	1V8	O	MIPI Display Serial Interface clock pair positive signal
X1_6	N6	GPIO1_IO07	GPIO1_IO07	3V3	I/O	General Purpose Input Output for MIPI Display Touchscreen Interupt
X1_66	T7	GPIO1_IO01	PWM1_OUT	3V3	I/O	General Purpose Input Output with PWM control for MIPI DSI Brightness Control
X1_68	N7	GPIO1_IO08	DSI_EN	3V3	I/O	General Purpose Input Output to enable MIP DSI Display

5.3. MIPI Camera

This section introduces the MIPI CSI-2 RX subsystem with the CSI-2 RX PHY and host controller. This subsystem handles the sensor/image input and process for all the input imaging devices.

The MIPI-CSI2 Controller has the following key features:

- Implements all three CSI-2 MIPI layers (Pixel to byte packing, low level protocol,
- Lane management)
- Supports unidirectional Master operation
- Transmitter and receiver versions
- Scalable data lane support, 1 to 4 Data Lanes
- Supports high speed mode(80Mbps - 1.5Gbps) per lane, providing 4K@30fps capability for the 4 lanes
- Supports 10Mbps data rate in low power mode
- Includes high speed deserializers
- Loopback testability support
- Support for all CSI-2 data types
- Virtual Channel support
- Support for DPHY Ultra Low Power State (ULPS)
- Error collection support (Rx Only)
- Flexible pixel-based user interface
- Supports user generated packets
- Supports single, double, or quad pixel interface
- Supports PHY Protocol Interface (PPI) compatible MIPI D-PHYs
- Delivered fully integrate and verified with target MIPI D-PHY
- RX Video Interface
- APB Control and Status Register (CSR) interface with IRQ support

Table 11 - MIPI Camera Control Signals

PIN	CPU BALL	CPU PAD NAME	Signal	V	I/O	Description
X2_65	L7	GPIO1_IO12	GPIO1_IO12	3V3	O	General Purpose Input Output for MIPI Camera reset
X2_69	J6	GPIO1_IO15	CLKO2	3V3	O	MIPI Camera input clock

Table 12 – MIPI Camera 1 Signal Description

PIN	CPU BALL	CPU PAD NAME	Signal	V	I/O	Description
X2_31	A22	CSI1_CLK_N	CSI_P1_CKN	1V8	O	MIPI Camera 1 Serial Interface clock pair negative signal
X2_33	B22	CSI1_CLK_P	CSI_P1_CKP	1V8	O	MIPI Camera 1 Serial Interface clock pair positive signal
X2_35	A23	CSI1_D0_N	CSI_P1_DN0	1V8	I	MIPI Camera 1 Serial Interface data pair 0 negative signal
X2_37	B23	CSI1_D0_P	CSI_P1_DP0	1V8	I	MIPI Camera 1 Serial Interface data pair 0 positive signal
X2_39	D22	CSI1_D1_P	CSI_P1_DP1	1V8	I	MIPI Camera 1 Serial Interface data pair 1 positive signal
X2_41	C22	CSI1_D1_N	CSI_P1_DN1	1V8	I	MIPI Camera 1 Serial Interface data pair 1 negative signal
X2_43	C23	CSI1_D2_P	CSI_P1_DP2	1V8	I	MIPI Camera 1 Serial Interface data pair 2 positive signal
X2_45	B24	CSI1_D2_N	CSI_P1_DN2	1V8	I	MIPI Camera 1 Serial Interface data pair 2 negative signal
X2_47	C21	CSI1_D3_N	CSI_P1_DN3	1V8	I	MIPI Camera 1 Serial Interface data pair 3 negative signal
X2_49	D21	CSI1_D3_P	CSI_P1_DP3	1V8	I	MIPI Camera 1 Serial Interface data pair 3 positive signal
X2_67	A6	UART3_RXD	GPIO5_IO26	3V3	O	General Purpose Input Output for MIPI Camera 1 power down

Table 13 – MIPI Camera 2 Signal Description

PIN	CPU BALL	CPU PAD NAME	Signal	V	I/O	Description
X1_3	C19	CSI2_D3_N	CSI_P2_DN3	1V8	I	MIPI Camera 2 Serial Interface data pair 3 negative signal
X1_4	B7	UART3_TXD	GPIO5_IO27	3V3	O	General Purpose Input Output for MIPI Camera 2 power down
X1_5	D19	CSI2_D3_P	CSI_P2_DP3	1V8	I	MIPI Camera 2 Serial Interface data pair 3 positive signal
X1_9	A19	CSI2_CLK_N	CSI_P2_CKN	1V8	I	MIPI Camera 2 Serial Interface clock pair negative signal
X1_11	B19	CSI2_CLK_P	CSI_P2_CKP	1V8	I	MIPI Camera 2 Serial Interface clock pair positive signal
X1_15	A21	CSI2_D2_N	CSI_P2_DN2	1V8	I	MIPI Camera 2 Serial Interface data pair 2 negative signal
X1_17	B21	CSI2_D2_P	CSI_P2_DP2	1V8	I	MIPI Camera 2 Serial Interface data pair 2 positive signal
X1_21	A20	CSI2_D1_N	CSI_P2_DN1	1V8	I	MIPI Camera 2 Serial Interface data pair 1 negative signal
X1_23	B20	CSI2_D1_P	CSI_P2_DP1	1V8	I	MIPI Camera 2 Serial Interface data pair 1 positive signal
X1_27	C20	CSI2_D0_N	CSI_P2_DN0	1V8	I	MIPI Camera 2 Serial Interface data pair 0 negative signal
X1_29	D20	CSI2_D0_P	CSI_P2_DP0	1V8	I	MIPI Camera 2 Serial Interface data pair 0 positive signal

5.4. Audio Interface

The PICO-IMX8M provides multiple I²S (or I²S) interfaces that support fullduplex serial interfaces with frame synchronization such as I2S, AC97, TDM, and codec/DSP interfaces.

The I²S Interface supports the following features:

- Transmitter with independent bit clock and frame sync supporting 1 data line
- Receiver with independent bit clock and frame sync supporting 1 data line
- Each data line can support a maximum Frame size of 32 words
- Word size of between 8-bits and 32-bits
- Word size configured separately for first word and remaining words in frame
- Asynchronous 128 × 32-bit FIFO for each transmit and receive data line
- Supports graceful restart after FIFO error
- Supports automatic restart after FIFO error without software intervention
- Supports packing of 8-bit and 16-bit data into each 32-bit FIFO word

For additional details, please refer to the “Synchronous Audio Interface (SAI)” chapter of the “i.MX8M Reference Manual”.

Table 14 - I²S-1 Audio Signal Description

PIN	CPU BALL	CPU PAD NAME	Signal	V	I/O	Description
E1_50	F3	SAI3_RXD	SAI3_RXD	1V8	I	Integrated Interchip Sound (I²S) channel receive data line
E1_52	C4	SAI3_TXC	SAI3_TXC	1V8	O	Integrated Interchip Sound (I²S) channel word clock signal
E1_54	G3	SAI3_TXFS	SAI3_TXFS	1V8	O	Integrated Interchip Sound (I²S) channel frame synchronization signal
E1_56	C3	SAI3_TXD	SAI3_TXD	1V8	O	Integrated Interchip Sound (I²S) channel transmit data line

Table 15 - I²S-2 Audio Signal Description

PIN	CPU BALL	CPU PAD NAME	Signal	V	I/O	Description
X2_19	G5	SAI2_TXD0	SAI2_TXD	3V3	O	Integrated Interchip Sound (I²S) channel transmit data line
X2_21	H6	SAI2_RXD0	SAI2_RXD	3V3	I	Integrated Interchip Sound (I²S) channel receive data line
X2_25	H4	SAI2_TXFS	SAI2_TXFS	3V3	O	Integrated Interchip Sound (I²S) channel frame synchronization signal
X2_27	J5	SAI2_TXC	SAI2_TXC	3V3	O	Integrated Interchip Sound (I²S) channel word clock signal

5.5. PCI Express

This block provides information regarding PCIe PHY and its features. PCIe PHY supports 6.0 Gbps data rate and complies to PCI Express base specification 2.1. The functions that are performed by the transceiver include serializing the 8B/10B encoded data for transmission, de-serializing received code groups, and word alignment.

When transmitting, the transceiver accepts two or four 10-bit 8B/10B encoded transmit characters, latches them and serializes the data onto the PCIE_TX_P/PCIE_TX_N differential outputs at 1.5 / 2.5 / 3.0 / 5.0 / 6.0 Gbps. It also performs 8B/10B encoding for 8-bit data from the PIPE interface.

When receiving, the transceiver also samples received serial data on the PCIE_RX_P / PCIE_RX_N differential inputs, deserializes it into two or four 10-bit received characters and detects the K28.5 character (0011111010 or 1100000101) for word alignment. It also applies 8B/10B decoding for 8-bit data to the PIPE interface. PCIe PHY core contains on-chip PLL circuitry for synthesis of the baud-rate transmitting clocks, and extraction of the retimed clocks from the received serial stream.

The following list the key features of the PCIe PHY:

- 1.5 / 2.5 / 3.0 / 5.0 / 6.0 Gbps Serializer / Deserializer
- Compliant with PCI Express Base Specification 2.1
- Compliant with PIPE Specification 2.0
- 8 / 16 / 20 / 40-bit CMOS Interface for Transmitter and Receiver
- 25 / 100 MHz Reference Clock
- K28.5 Detection for Word Alignment
- 8B/10B Encoding / Decoding
- Receiver Detection
- Supports Spread Spectrum Clocking in Transmitter and Receiver

Table 16 - PCI Express Signal Description

PIN	CPU BALL	CPU PAD NAME	Signal	V	I/O	Description
X2_56	T22	CLK2_P	PCIE2_CLKP	3V3	O	PCI Express clock differential pair positive signal
X2_58	U22	CLK2_N	PCIE2_CLKN	3V3	O	PCI Express clock differential pair negative signal
X2_62	E25	PCIE2_TXN_P	PCIE2_TXP	3V3	O	PCI Express Receive input differential pair positive signal
X2_64	E24	PCIE2_TXN_N	PCIE2_TXN	3V3	O	PCI Express Receive input differential pair negative signal
X2_68	D25	PCIE_RXN_P	PCIE2_RXP	3V3	I	PCI Express Receive input differential pair positive signal
X2_70	D24	PCIE_RXN_N	PCIE2_RXN	3V3	I	PCI Express Receive input differential pair negative signal

NOTE: The PCIE_TX pair has decoupling capacitors on the PICO Compute Module valued 10nF

5.6. Universal Serial Bus (USB) Interface

The PICO-IMX8M incorporates a single USB Host controller and an additional USB Host/OTG controller.

Each of the USB controllers provides the following main features:
USB 2.0 Host/OTG Controller

- High-Speed/Full-Speed/Low-Speed OTG core
- HS/FS/LS UTMI compliant interface
- High Speed, Full Speed and Low Speed operation in Host mode (with UTMI transceiver)
- High Speed, and Full Speed operation in Peripheral mode (with UTMI transceiver)
- Hardware support for OTG signaling, session request protocol, and host negotiation protocol
- Support charger detection

USB 2.0 Host Controller

- High-Speed/Full-Speed/Low-Speed Host-Only core
- HS/FS/LS UTMI compliant interface

For additional details, please refer to the “Universal Serial Bus Controller (USB)” chapter of the “i.MX8M Application Processor Reference Manual”.

Table 17 - USB Host Signal Description

PIN	CPU BALL	CPU PAD NAME	Signal	V	I/O	Description
X2_46	B10	USB2_DN	USB2_DN	3V3	I/O	Universal Serial Bus differential pair negative signal
X2_48	A10	USB2_DP	USB2_DP	3V3	I/O	Universal Serial Bus differential pair positive signal
X2_50	D9	USB2_VBUS	USB2_VBUS	5V	I	Universal Serial Bus power
X2_52	P7	GPIO1_IO05	GPIO1_IO05	3V3	I	General Purpose Input Output for Active low input, to inform USB overcurrent condition (low = overcurrent detected)

Table 18 - USB OTG Signal Description

PIN	CPU BALL	CPU PAD NAME	Signal	V	I/O	Description
E1_3	C14	USB1_ID	USB1_ID	3V3	I	USB OTG ID Pin
E1_16	A14	USB1_DP	USB1_DP	3V3	I/O	Universal Serial Bus differential pair positive signal
E1_18	B14	USB1_DN	USB1_DN	3V3	I/O	Universal Serial Bus differential pair negative signal
E1_19	G4	SAI3_RXFS	GPIO4_IO28	1V8	I	Over current detect input pin to monitor USB power over current
E1_20	D14	USB1_VBUS	USB_VBUS	5V	I	Universal Serial Bus power
E1_21	M20	NAND_DQS	GPIO3_IO14	1V8	O	Universal Serial Bus power enable

NOTE: While using USB OTG in USB HOST mode. The USB_ID pin should have a pull-down resistor to GND.

5.7. SDIO/MMC Interface

The PICO-IMX8M features a MMC / SD / SDIO host interfaces connected to the NXP i.MX8M integrated “Ultra Secured Digital Host Controller” (uSDHC).

The following main features are supported by uSDHC:

- Conforms to the SD Host Controller Standard Specification version 3.0
- Compatible with the MMC System Specification version 4.2/4.3/4.4/4.41/4.5/5.0
- Compatible with the SD Memory Card Specification version 3.0 and supports the Extended Capacity SD Memory Card
- Compatible with the SDIO Card Specification version 3.0
- Designed to work with SD Memory, miniSD Memory, SDIO, miniSDIO, SD Combo, MMC, MMC plus, and MMC RS cards
- Card bus clock frequency up to 208 MHz
- Supports 1-bit / 4-bit SD and SDIO modes, 1-bit / 4-bit / 8-bit MMC modes

The MMC/SD/SDIO host controller can support a single MMC / SD / SDIO card or device.

For additional details, please refer to the “Ultra Secured Digital Host Controller (uSDHC)” chapter of the “i.MX8M Reference Manual”.

Table 19 - SDIO Signal Description

PIN	CPU BALL	CPU PAD NAME	Signal	V	I/O	Description
E1_29	P5	GPIO1_IO04	GPIO1_IO04	3V3	O	SD Card voltage select
E1_49			NVCC_SD	1V8 / 3V3	P	SD Card power
E1_58	L22	SD2_CLK	SD2_CLK	1V8/ 3V3	O	MMC/SDIO Clock
E1_60	L21	SD2_CD_B	SD2_CD	1V8/ 3V3	I	SD Card detect input (Active low)
E1_62	M22	SD2_CMD	SD2_CMD	1V8/ 3V3	I/O	MMC/SDIO Command
E1_64	P22	SD2_DATA2	SD2_DATA2	1V8/ 3V3	I/O	MMC/SDIO Data bit 2
E1_66	N22	SD2_DATA0	SD2_DATA0	1V8/ 3V3	IO	MMC/SDIO Data bit 0
E1_68	P21	SD2_DATA3	SD2_DATA3	1V8/ 3V3	I/O	MMC/SDIO Data bit 3
E1_70	N21	SD2_DATA1	SD2_DATA1	1V8/ 3V3	I/O	MMC/SDIO Data bit 1

NOTE : The SD2 interface is only available in configurations that do not have the Wi-Fi / Bluetooth module option installed.

5.8. Universal Asynchronous Receiver/Transmitter (UART) Interface

The PICO-IMX8M Universal Asynchronous Receiver/Transmitter (UART) provides serial communication capability with external devices through a level converter.

The UART includes the following features:

- High-speed TIA/EIA-232-F compatible.
- 7- or 8-bit data words, 1 or 2 stop bits, programmable parity (even, odd or none).
- Programmable baud rates up to 4 Mbps.
- 32-byte FIFO on Tx and 32 half-word FIFO on Rx supporting auto-baud.
- Serial IR interface low-speed, IrDA-compatible (up to 115.2 Kbit/s).
- Hardware flow control support for a request to send and clear to send signals.
- RS-485 driver direction control.
- DCE/DTE capability.
- RX_DATA input and TX_DATA output can be inverted respectively in RS-232/RS-485 mode.
- Various asynchronous wake mechanisms with the capability to wake the processor from STOP mode through an on-chip interrupt.

For additional details, please refer to the “Universal Asynchronous Receiver/Transmitter (UART)” chapter of the “i.MX8M Application Processor Reference Manual”.

Table 20 - UART Signal Description

PIN	CPU BALL	CPU PAD NAME	Signal	V	I/O	Description
E1_22	C7	UART1_RXD	UART1_RXD	1V8	I	Universal Asynchronous Receive Transmit receive data signal
E1_27	A7	UART1_TXD	UART1_TXD	1V8	O	Universal Asynchronous Receive Transmit transmit data signal
E1_46	E5	ECSPI2_MOSI	UART4_TXD	1V8	O	Universal Asynchronous Receive Transmit transmit data signal
E1_61	C5	ECSPI2_SCLK	UART4_RXD	1V8	I	Universal Asynchronous Receive Transmit receive data signal
E1_63	A5	ECSPI2_SS0	UART4_RTS	1V8	O	Universal Asynchronous Receive Transmit request to send signal
E1_65	B5	ECSPI2_MISO	UART4_CTS	1V8	O	Universal Asynchronous Receive Transmit clear to send signal

NOTE: it is recommended to use the UART1 interface as system debug where possible and use the UART4 signals in applications where one serial port is required.

5.9. Serial Peripheral Interface (SPI)

The PICO-IMX8M has an onboard SPI interface that can operate in either master or SPI slave mode.

The SPI Interface includes the following features :

- Data rate up to 52 Mbit/s.
- Full-duplex synchronous serial interface.
- Master/Slave configurable.
- Up-to four chip select signals to support multiple peripherals.
- Transfer continuation function allows unlimited length data transfers.
- 32-bit wide by 64-entry FIFO for both transmit and receive data.
- Polarity and phase of the Chip Select (SS) and SPI Clock (SCLK) are configurable.
- Direct Memory Access (DMA) support.

For additional details, please refer to the “Enhanced Configurable SPI (ECSPI)” chapter of the “i.MX8M Application Processor Reference Manual”.

Table 21 - SPI Signal Description

PIN	CPU BALL	CPU PAD NAME	Signal	V	I/O	Description
E1_51	G21	NAND_CE1_B	ECSPI1_SS1	1V8	O	Serial Peripheral Interface Chip Select 1 signal
E1_53	D4	ECSPI1_SS0	ECSPI1_SS0	1V8	O	Serial Peripheral Interface Chip Select 0 Signal
E1_55	D5	ECSPI1_SCLK	ECSPI1_SCLK	1V8	O	Serial Peripheral Interface clock signal
E1_57	A4	ECSPI1_MOSI	ECSPI1_MOSI	1V8	O	Serial Peripheral Interface master output slave input signal.
E1_59	B4	ECSPI1_MISO	ECSPI1_MISO	1V8	I/O	Serial Peripheral Interface master input slave output signal

5.10. I²C Bus

The PICO-IMX8M incorporates several I²C interfaces. I²C is a two-wire, bidirectional serial bus that provides a simple, efficient method of data exchange, minimizing the interconnection between devices. This bus is suitable for applications requiring occasional communications over a short distance between many devices.
The following features are supported:

- Compliance with Philips I2C specification version 2.1
- Multiple-master operation
- Support for standard mode (up to 100K bits/s) and fast mode (up to 400K bits/s)
- Arbitration-lost interrupt with automatic mode switching from master to slave

For additional details, please refer to the "I²C Controller (I²C)" chapter of the "i.MX8M Application Processor Reference Manual".

Table 22 - I²C Bus Signal Description

PIN	CPU BALL	CPU PAD NAME	Signal	V	I/O	Description
E1_41	G7	I2C2_SCL	I2C2_SCL	1V8	O	I2C bus clock line
E1_43	F7	I2C2_SDA	I2C2_SDA	1V8	I/O	I2C bus data line
E1_45	G8	I2C3_SCL	I2C3_SCL	1V8	O	I2C bus clock line
E1_47	E9	I2C3_SDA	I2C3_SDA	1V8	I/O	I2C bus data line

NOTE: All 1V8 I²C bus data and clock lines for all I²C interfaces have 2.2K Ω pull-up resistors present on the PICO-IMX8M module.

NOTE: All 3V3 I²C bus data and clock lines for all I²C interfaces have 1.5K Ω pull-up resistors present on the PICO-IMX8M module.

5.11. General Purpose Input / Output (GPIO)

The PICO-IMX8M has 10 dedicated GPIO pins at 1.8V. Many of the other pins used on the PICO Compute Module can be put in GPIO module however doing so might break scalability with other PICO Compute Modules.
The GPIO signals can be configured for the following applications:

- Data input / output
- Interrupt generation

For additional details, please refer to the “General Purpose Input / Output (GPIO)” chapter of the “i.MX8M Application Processor Reference Manual”.

Table 23 - GPIO Signal Description

PIN	CPU BALL	CPU PAD NAME	Signal	V	I/O	Description
E1_24	H19	NAND_CE0_B	GPIO3_IO01	1V8	I/O	General Purpose Input Output
E1_25	F21	AND_CE2_B	GPIO3_IO03	1V8	I/O	General Purpose Input Output
E1_26	H20	NAND_CE3_B	GPIO3_IO04	1V8	I/O	General Purpose Input Output
E1_28	G19	NAND_ALE	GPIO3_IO00	1V8	I/O	General Purpose Input Output
E1_30	H21	NAND_CLE	GPIO3_IO05	1V8	I/O	General Purpose Input Output
E1_32	K19	NAND_RE_B	GPIO3_IO15	1V8	I/O	General Purpose Input Output
E1_34	K22	NAND_WE_B	GPIO3_IO17	1V8	I/O	General Purpose Input Output
E1_42	K21	NAND_WP_B	GPIO3_IO18	1V8	I/O	General Purpose Input Output
E1_44	K20	NAND_READY_B	GPIO3_IO16	1V8	I/O	General Purpose Input Output
E1_48	G20	NAND_DATA00	GPIO3_IO06	1V8	I/O	General Purpose Input Output

5.12. Pulse Width Modulation (PWM)

The Pulse Width Modulation (PWM) has a 16-bit counter, and is optimized to generate sound from stored sample audio images and it can also generate tones. It uses 16-bit resolution and a 4 x 16 data FIFO.

The PICO-IMX8M has 4 dedicated PWM pins at 1.8V.

The following features characterize the PWM:

- 16-bit up-counter with clock source selection
- 4 x 16 FIFO to minimize interrupt overhead
- 12-bit pre-scaler for division of clock
- Sound and melody generation
- Active high or active low configured output
- Can be programmed to be active in low-power mode
- Can be programmed to be active in debug mode
- Interrupts at compare and rollover

For additional details, please refer to the “Pulse Width Modulation (PWM)” chapter of the “i.MX8M Application Processor Reference Manual”.

Table 24 - PWM Signal Description

PIN	CPU BALL	CPU PAD NAME	Signal	V	I/O	Description
E1_33	G6	SPDIF_RX	PWM2_OUT	1V8	O	General Purpose Input Output with PWM control
E1_35	E6	SPDIF_EXT_CLK	PWM1_OUT	1V8	O	General Purpose Input Output with PWM control
E1_37	F6	SPDIF_TX	PWM3_OUT	1V8	I/O	General Purpose Input Output with PWM control
E1_39	D3	SAI3_MCLK	PWM4_OUT	1V8	O	General Purpose Input Output with PWM control

NOTE: When using PWM1_OUT for MIPI DSI Brightness Control on connector X1 PIN 66. This pin can only be set in GPIO mode to avoid conflicts.

5.13. Manufacturing and Boot Control

The PICO-IMX8M has a number of pins to override the default boot media present on the PICO-IMX8M Compute Module or enable debug serial loader functionality.

Table 25 - Boot Selection Pins

PIN	CPU BALL	CPU PAD NAME	Signal	V	I/O	Description
X2_3	J1	SAI1_RXD4	BT_CFG4	3V3	I	Boot Select pin
	B2	SAI1_TXD2	BT_CFG10	3V3	I	Boot Select pin
	D2	SAI1_TXD4	BT_CFG12	3V3	I	Boot Select pin
X2_5	W6	BOOT_MODE0	BOOT_MODE0	3V3	I	Boot Mode0 select
X2_7	C2	SAI1_TXD5	BT_CFG13	3V3	I	Boot Select pin
	F1	SAI1_RXD5	BT_CFG5	3V3		Boot Select pin
X2_9	V6	BOOT_MODE1	BOOT_MODE1	3V3	I	Boot Mode1 select

5.13.1. eMMC Boot Mode

The PICO-IMX8M Compute Module automatically boot from the internal eMMC if the all control signals keep floating or if the pins are connected as follow:

Table 25 – eMMC Boot Mode Configuration

PIN	CPU BALL	eMMC Boot Mode
X2_3	J1	LOW
	B2	LOW
	D2	LOW
X2_5	W6	Not Connected
X2_7	C2	HIGH
	F1	HIGH
X2_9	V6	Not Connected

5.13.2. Serial Downloader Boot Mode

To boot the PICO-IMX8M in Serial Download Mode. The boot signals need to be connected as

Table 26 - Serial Downloader Boot Mode Configuration

PIN	CPU BALL	Serial Downloader Mode
X2_3	J1	Not Connected
	B2	Not Connected
	D2	Not Connected
X2_5	W6	HIGH
X2_7	C2	Not Connected
	F1	Not Connected
X2_9	V6	LOW

5.13.3. SD Card Boot Mode

For configurations of the PICO-IMX8M that do not incorporate a Wi-Fi / Bluetooth option can boot from a SD cardslot on the carrier board by setting the boot mode control pins as follow:

Table 27 - SD Card Boot Mode Configuration

PIN	CPU BALL	SD Boot Mode
X2_3	J1	HIGH
	B2	HIGH
	D2	HIGH
X2_5	W6	Not Connected
X2_7	C2	LOW
	F1	LOW
X2_9	V6	Not Connected

5.15. Input Power Requirements

The PICO-IMX8M is designed to be driven with a single input power rail.
The power domain pins have to be connected as follow:

- All GND pins have to be connected to the carrier board ground pane.
- All VSYS pins should be connected to the main power source.

Table 28 - Input Power Signals

POWER Rail	Norminal Input	Input Range	Maximum Input Ripple
VSYS (4pin)	5V	+4.2V to +5.25V	+/- 50mV

5.15.1. Power Management Signals

The PICO-IMX8M has the following set of signals to control the system power states such as the power-on and reset conditions. This enables the system designer to implement a fully ACPI compliant system supporting system states.

Table 29 - Power Management Signals

PIN	CPU BALL	CPU PAD NAME	Signal	V	I/O	Description
E1_17	W21	ON_OFF	ON_OFF	3V3	I	Power ON button input signal
E1_36			RESET IN	1V8	I	Reset power signal

6. Ordering Information

TechNexion provides a complete product portfolio for the PICO-IMX8M to assist our customers to evaluate, proto-type, integrate and mass produce solutions with our PICO Compute Modules.

6.1. PICO Compute Module Product Ordering Part Numbers

The PICO-IMX8M is available in a number of standard configurations. Custom tailored versions with other memory configuration, de-population of interfaces or extended and industrial temperature options are available upon request.

Standard part numbers can be easily found on the PICO-IMX8M product page on the TechNexion corporate homepage.

6.2. Custom Part Number Rule

The PICO-IMX8M can be ordered in custom tailored configuration to meet special application requirements and conditions according to the following custom part number creation rules.

Custom part numbers carry minimum order quantities (MOQ). Please connect with your TechNexion distributor or account manager for conditions and availability.

Part number format: **PICO-IMX8Mx-xx-Rxx-Exx-xxxx-xx-xxxx**

Interface	Code	Description
	IMX8MQ	NXP i.MX8MQuad
Processor Speed	13	1.3GHz
	15	1.5GHz
Memory	R10	1GB LPDDR4
	R20	2GB LPDDR4
	R30	3GB LPDDR4
	R40	4GB LPDDR4
Storage	E16	eMMC 16GB
	EXX	eMMC other capacity
Wi-Fi / Bluetooth	-	-
	9377	Qualcomm QCA9377 802.11a/b/g/n/ac (2.4 + 5GHz) + Bluetooth 4.1
Temperature Range	-	Commercial Temperature range (0° to +60° C) (Default)
	TE	Extended Temperature range (-20° to +70° C)
	TI	Industrial Temperature range (-40° to +85° C)
Custom ID	XXXX	Custom Part number ID for customized software loader and special component (BOM)

7. Important Notice

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TechNexion Ltd.
16F-5, No. 736, Zhongzheng Road,
ZhongHe District, 23511, New Taipei City, Taiwan
Phone : +886-2-82273585
Fax : +886-2-82273590
E-mail : sales@TechNexion.com
Web : https://www.TechNexion.com/